



Modbus/TCP interface SINEAX CAM

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The basics of the **MODBUS®** communication are summarized in the document "**Modbus Basics. PDF**"
(see CAM documentation CD or on our website <http://www.camillebauer.com>)

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Modificat.	Date	Vis.:	Type: SINEAX CAM	Nr.: 1 / 34	Author: 06.05.09 RR
			Description: Modbus/TCP interface	No.: W 157471	

1. Bus connection

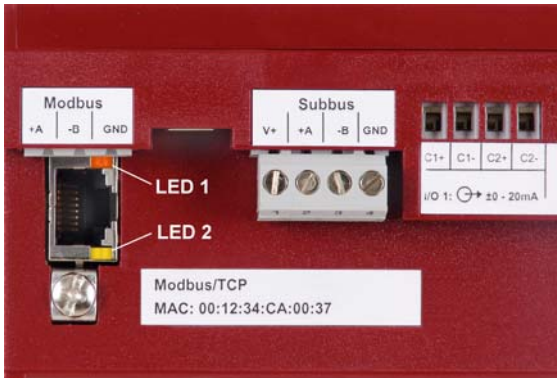
1.1 Connection

Before devices can be connected to an existing Ethernet network, you have to ensure that they will not disturb the normal network service. The rule is:



None of the devices to connect is allowed to have the same IP address than another device already installed

The factory setting of the IP address of CAM is: 192.168.1.101



The standard RJ45 connector serves for direct connecting an Ethernet cable. If the PC is directly connected to the device a cross-wired cable must be used.

To prevent possible EMC problems the shield of the cable can be connected to earth via screw connector.

The network installation of the devices is done by means of the CB-Manager software. As soon as all devices have a unique network address they may be accessed by means of a suitable Modbus master client.

- Interface: RJ45 connector, Ethernet 100BaseTX
- Mode: 10/100 MBit/s, full / half duplex, Auto-negotiation
- Protocols: Modbus/TCP, NTP

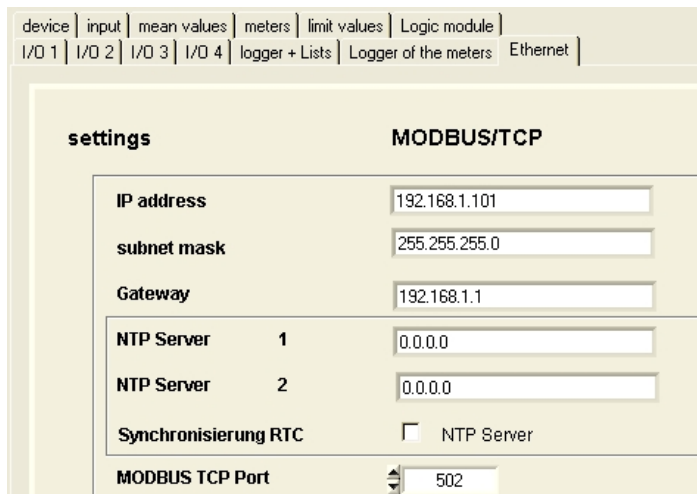
Function of the LEDs

LED 1 (orange)	<ul style="list-style-type: none"> ▪ ON as soon as a network connection exists ▪ Flashing when data is transmitted via Ethernet connection
LED 2 (yellow)	<ul style="list-style-type: none"> ▪ Flashing with 1 Hz: Start-up part 1 (boot loader) ▪ Flashing with 0.5Hz: Start-up part 2 (operating system and device services) ▪ ON during Modbus/TCP communication with the device

1.2 Network installation using the CB-Manager software

The setting of the network parameters of the device may be done via a local interface (USB and RS485) or directly via the Ethernet interface.

Installation via a local interface

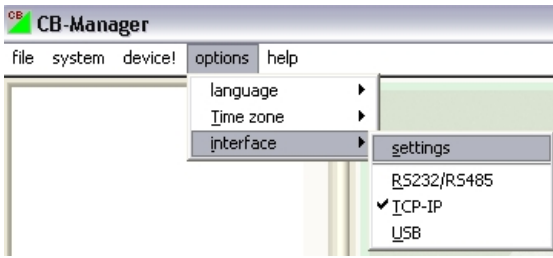


The network settings are part of the device configuration (register "Ethernet") and have to be arranged with the network administrator:

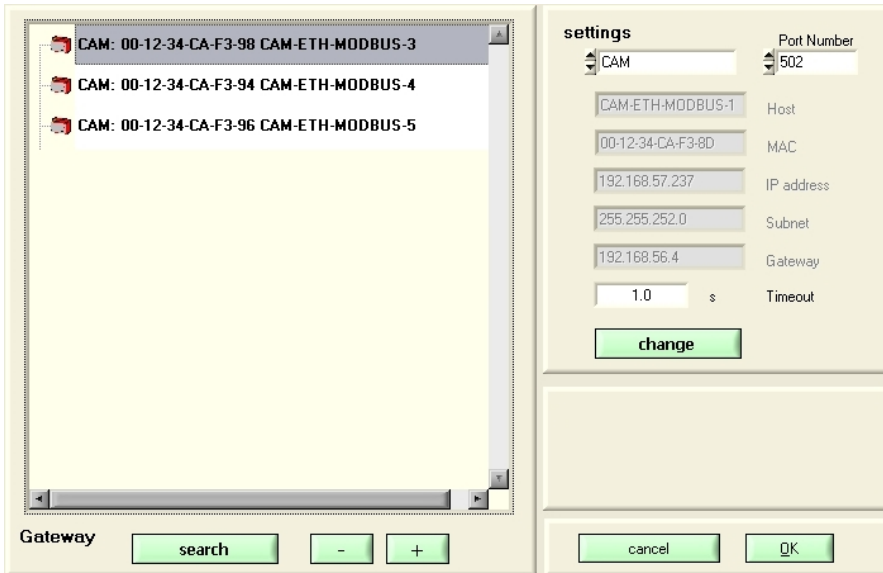
- **IP address**: This one must be **unique**, i.e. may be assigned in the network only once.
- **Subnet mask**: Defines how many devices are directly addressable in the network. This setting is equal for all the devices.
- **Gateway**: Is used to resolve addresses during communication between different networks. Should contain a valid address within the own network.

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Installation via Ethernet interface



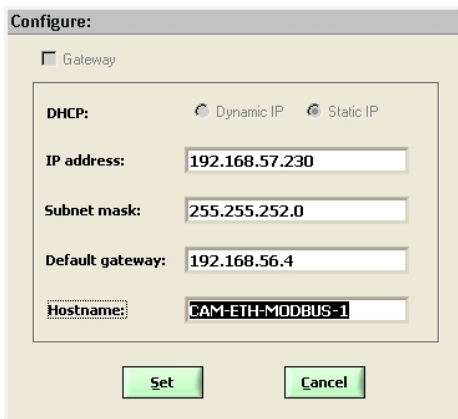
Select "settings" under options | interface. The interface type has to be set to "TCP-IP".



Devices in the local network

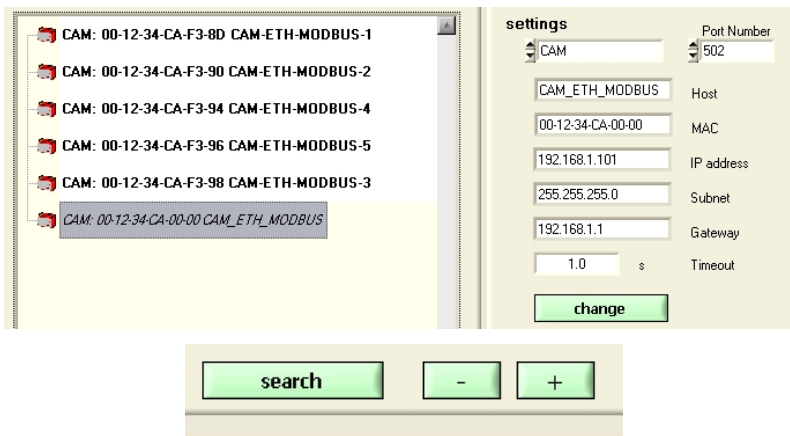
Set settings to "CAM". All devices connected in the local network will be searched using a UDP broadcast telegram, which identifies the devices by means of their MAC address. A clear identification of each device is possible by means of its unique MAC address, which is shown on the device (see chapter 1.1).

Now to each device a **unique** network address must be assigned. To do so select a device from the list and click on "change".



The following settings have to be arranged with the network administrator:

- **IP address:** This one must be **unique**, i.e. may be assigned in the network only once.
- **Subnet mask:** Defines how many devices are directly addressable in the network. This setting is equal for all the devices.
- **Default gateway:** Is used to resolve addresses during communication between different networks. Should contain a valid address within the own network.
- **Hostname:** Individual designation for each device. Helps to identify the device in the device list.



Devices outside the local network

Devices which are not in the same network as the PC (e.g. in the Internet) can not be found and have to be added manually to the device list by means of **+**. To each entry you have to assign a unique IP and MAC address, which are different from the initial value. Otherwise it's not possible to add further entries.

The setting of the network parameters must be performed before mounting the device. As an alternative this may be done in the destination network via a local interface or via Ethernet.

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1.4 TCP ports for data transmission

TCP ports

The TCP communication is done via so-called ports. The number of the used port allows determining the type of communication. As a standard Modbus/TCP communication is performed via TCP port 502, NTP uses port 123. However, the port for the Modbus/TCP telegrams may be modified. You may provide a unique port to each of the devices, e.g. 503, 504, 505 etc., for an easier analysis of the telegram traffic. The setting of the Modbus TCP port is done as shown above. Independent of these setting a communication via port 502 is always supported. The device allows at least 5 connections to different clients at the same time.

Firewall

Due to security reasons nowadays each network is protected by means of a firewall. When configuring the firewall you have to decide which communication is desired and which have to be blocked. The TCP port 502 for the Modbus/TCP communication normally is considered to be unsafe and is very often disabled. This may lead to a situation where no communication between networks (e.g. via Internet) is possible.

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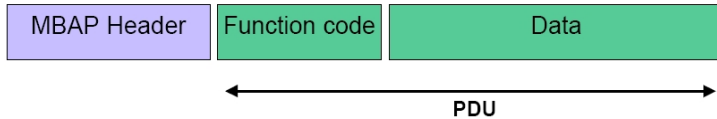
2. Coding and addressing

Addressing

Within the telegrams transmitted all data addresses are zero based. The first data element is always accessed via address 0. For example the coil, which is known as "Coil 1" of the device, is accessed as "Coil 0" within the telegram. Coil 127 is addressed as 0x007E.

The holding register 40001 is addressed as register 0 within the telegram. The function code of the telegram itself gives the information, that a "holding register" is accessed. Therefore the „4XXXX“ information is implicit. The holding register 40108 is addressed as 0x006B (107 decimal).

Telegrams



The information to transmit is the same for Modbus/TCP as for Modbus/RTU telegrams, displayed in green above. The addressing of the devices is done by means of the IP address and replaces the previous Modbus address. The check sum is dropped, because the security of the transmission is assured on TCP communication level.

Bit information

Bits are represented within a byte in a conventional way, MSB (Bit 7) on the most left and LSB (Bit 0) most right (0101'1010 = 0x5A = 90). An example to read Coil 20 up to 40 of slave 17:

Byte	Request	Answer
0	Slave address	0x11
1	Function code	0x01
2	Start address	0x00
3	19 = Coil 20	0x13
4	Number	0x00
5	20...40 = 21	0x15

The start address of the request plus the bit position in the answer byte 0 corresponds to the coil address. Started bytes are filled with zeros. Coil 27...20 = 0xCD = 11001101b → Coil20 = ON, Coil21 = OFF, Coil22 = ON, etc.

Byte information

Modbus doesn't know a data type Byte or Character (see address space). Strings or byte arrays will be mapped into holding registers (2 bytes per register) and transferred as „Character streams“, e.g. „Hello World“

Register	HEX	char
40101	0x4865	,H ,e'
40102	0x6C6C	,l' ,l'
40103	0x6F5F	,o' ,o'

Word

Register or words will be transferred in accordance with the „Big Endian“ format. An example to read Holding Register 40101 of Slave 17:

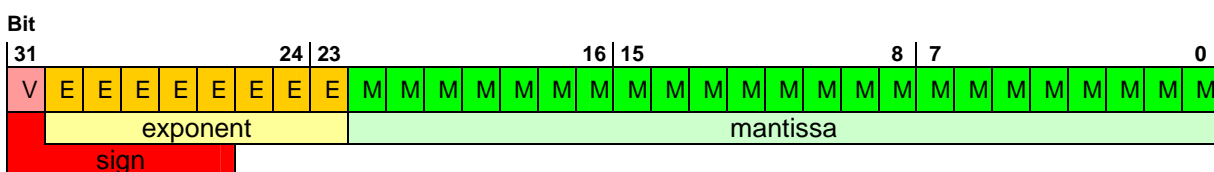
Byte	Request	Answer
0	Slave address	0x11
1	Function code	0x03
2	Start address	0x00
3	100= Register 101	0x64
4	Number	0x00
5	1 Register	0x01

Float (REAL)

There is no representation for floating point numbers in the Modbus specification. But as a matter of principle any desired data structure can be casted to a sequence of 16 bit registers. The IEEE 754 Standard as the most often used standard for the representation of floating numbers is normally used.

The first register contains the bits 15 – 0 of the 32 bit number (bit 0...15 of the mantissa).

The second register contains the bits 16 – 32 of the 32 bit number (sign, exponent and bit 16- 22 of the mantissa).



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3. Mapping

ADDRESS SPACE

The address space may be divided in 4 address spaces in accordance with the 4 data types.

Space	r / w	Address range	Function code	
Coil	readable writable	00001 – 09999	0x01 0x05 0x0F	Read Coil Status Force Single Coil ¹⁾ Force Multiple Coils
Discrete input	read only	10001 – 19999	0x02	Read Input Status
Input register	read only	30001 – 39999	0x04	Read Input Register ¹⁾
Holding register	readable writable	40001 – 49999	0x03 0x06 0x10	Read Holding Register Force Single Register ¹⁾ Preset Multiple Register

1) not implemented

To reduce the number of commands the device image has been mapped using „Holding register“ if possible. Information normally addressed as a single bit are implemented as „Coil“ or „Discrete input“.

SEGMENTS

Address	Description	Allowed function codes	
40001 – 40017 40100 – 40187 40190 – 40196 40200 – 40493 40500 – 40667 40670 – 40984 41025 – 41025 41030 – 41173 41180 – 41323 41330 – 41345 41362 – 41369 42956 – 42956 43917 – 43924	Device information General instantaneous values Instantaneous values harmonic analysis Instantaneous values of harmonics Minimum / Maximum values Maximum values THD, TDD and harmonics Tariff of standard meters Mean values, interval time t ₁ Mean values, interval time t ₂ Instantaneous values analog input Instantaneous values analog output Instantaneous values limit values Instantaneous values logic functions	0x03	Read Holding Register
41400 – 41459 41460 – 41484 41550 – 41562 41600 – 41602 42000 – 42015 42020 – 42121 42200 – 42215 42420 – 42493 42600 – 42663 42700 – 42955 43100 – 43920 44300 – 44301 44900 – 44911	Meter contents + scaling factors of I/O meters Meter contents + scaling factor standard meters RTC Simulation mode Serial numbers device, bus card, I/Os Parameters security system / general Measurement input parameters I/O parameters Mean value parameters Limit value parameters + state information Logic module parameters tariff allocation I/O meters Parameters of the Ethernet bus card	0x03 0x10	Read Holding Register Preset Multiple Register
10003 – 10014	Digital inputs	0x02	Read Input Status
00001 – 00014 00015	Relays + Digital IO's Tariff situation	0x01	Read Coil Status
00001 – 00014 00500 – 00541 00670 – 00676 01030 – 01077 01400 – 01423 01460 – 01471	Relays + digital outputs Reset of minimum / maximum values Reset maximum values THD, TDD, harmonics Reset minimum/maximum of mean-values Reset of I/O meters Reset of standard meters	0x0F	Force Multiple Coils

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USED SYNTAX

Address	Start address of described data blocks (Register, Coil or Input Status)
Time	Register address of a timestamp, typically a minimum / maximum value
Value	Register address of a measured quantity, typically a minimum / maximum value
Reset coil	Coil register address to reset a corresponding measured quantity
Name	Unique name of a variable or structure
Data type	Data type of variable U: unsigned INT: integer with 8, 16 or 32 Bit REAL (float) CHAR[..] TIME: seconds since 1.1.1970
#	Offset from the start address in the unit of the data type, for byte information: low byte 0, high byte 1
Default	Value when delivering or following a hardware reset
Description	Exact description of variable
14 2L 3G 3U 4U	Availability of the measured quantities, depending on the connected system 14 =Single phase system or 4-wire balanced load 2L =two phase system (split phase) 3G=3-wire balanced load 3U=3-wire unbalanced load or 3-wire unbalanced load Aron 4U =4-wire unbalanced

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4. Device information

Address	Name	Data type	#	Default	Description																		
40001	HW_IO_CONF	UINT8	0	255	I/O module 1 <div style="text-align: right;"> analog: 1 = bipolar digital: 1 = configurable as input or output </div> <div style="text-align: center;"> <pre> 7 6 5 4 3 2 1 0 └─┬─┘ └─┬─┘ Analog input/output Digital input/output 4: 0..20mA 0: not used Digital input/output 1: Analog output 0: 24VDC 2: Analog input 5: 125VDC 3: Digital input 2: 24VAC 4: Digital output 5: HV input </pre> </div>																		
			1	255	I/O module 2 as module 1																		
			2	255	I/O module 3 as module 1																		
			3	255	I/O module 4 as module 1																		
40003	HW_DISPLAY	UINT8	0	0	<table border="1"> <thead> <tr> <th>Value</th> <th>Meaning</th> </tr> </thead> <tbody> <tr><td>0</td><td>not used</td></tr> <tr><td>1</td><td>small display</td></tr> <tr><td>2</td><td>large display</td></tr> </tbody> </table>	Value	Meaning	0	not used	1	small display	2	large display										
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0	not used																						
1	Ethernet																						
2	PROFIBUS																						
40004	HW_OPTIONS	UINT16	0	0xD0	<table border="1"> <thead> <tr> <th>Bit</th> <th>Meaning</th> </tr> </thead> <tbody> <tr><td>0</td><td>Logger 1 and 2</td></tr> <tr><td>1</td><td>Operator list</td></tr> <tr><td>2</td><td>Power quality</td></tr> <tr><td>3</td><td>Disturbance recorder</td></tr> <tr><td>4</td><td>Real time clock (RTC)</td></tr> <tr><td>5</td><td>Flash</td></tr> <tr><td>6</td><td>Relays</td></tr> <tr><td>7</td><td>Neutral measurement</td></tr> </tbody> </table>	Bit	Meaning	0	Logger 1 and 2	1	Operator list	2	Power quality	3	Disturbance recorder	4	Real time clock (RTC)	5	Flash	6	Relays	7	Neutral measurement
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6	Relays																						
7	Neutral measurement																						
40005	NLB_NR	UINT16	0	0	NLB number (non-official versions)																		
40006	FV_INPUT	UINT16	0	214	Firmware version measurement part (214 = 2.14)																		
40007	FV_OUTPUT	UINT16	0	102	Firmware version analysis unit (102 = 1.02)																		
40008	FV_COM	UINT16	0	0	Firmware version communication unit (101 = 1.01)																		
40009	FV_MODUL	UINT16	0	102	Firmware version module 1 (102 = 1.02)																		
			1	102	Module 2 as module 1																		
			2	102	Module 3 as module 1																		
			3	102	Module 4 as module 1																		
40013	FV_DISPLAY	UINT16	0	0	Firmware version small display																		
			1	0	Firmware version large display																		
40015	HW_FREQ	UINT16	0	5000	Calibration frequency (5000 = 50.00Hz)																		
40016	CFG_DIGIO	UINT16	0	0	Configuration of digital IO modules (writable !!!) <table border="1"> <thead> <tr> <th>Bit</th> <th>Meaning (0 = input, 1 = output)</th> </tr> </thead> <tbody> <tr><td>0</td><td>Module 1</td></tr> <tr><td>1</td><td>Module 2</td></tr> <tr><td>2</td><td>Module 3</td></tr> <tr><td>3</td><td>Module 4</td></tr> </tbody> </table>	Bit	Meaning (0 = input, 1 = output)	0	Module 1	1	Module 2	2	Module 3	3	Module 4								
Bit	Meaning (0 = input, 1 = output)																						
0	Module 1																						
1	Module 2																						
2	Module 3																						
3	Module 4																						
40017	OPTION_EN	UINT128	0	0	Code for activating options																		

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Address	Name	Data type	#	Default	Description																
42000	SERIAL_NR	UINT32	0	0	Serial number / consecutive number of the basic device High register: <div style="text-align: center;"> <table border="1" style="display: inline-table; border-collapse: collapse;"> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> </table> <div style="display: flex; justify-content: space-around; width: 100%;"> Year - 2000 Month Day </div> </div>	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
15			14	13	12	11	10	9	8	7	6	5	4	3	2	1	0				
42002			1	0	Serial number bus card (as basic device)																
42004			2	0	Serial number module 1 (as basic device)																
42006			3	0	Serial number module 2 (as basic device)																
42008			4	0	Serial number module 3 (as basic device)																
42010			5	0	Serial number module 4 (as basic device)																
42012			6	0	Serial number small display unit (as basic device)																
42014	7	0	Serial number large display unit (as basic device)																		

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5. Measurements

5.1 General instantaneous values

Address	Name	14	2L	3G	3U	4U	Data type	#	Default	Description
40100	U	•	•	-	-	-	REAL	0	0.0	System voltage
40102	U1N	-	•	-	-	•		1	0.0	Voltage phase L1 to N
40104	U2N	-	•	-	-	•		2	0.0	Voltage phase L2 to N
40106	U3N	-	-	-	-	•		3	0.0	Voltage phase L3 to N
40108	U12	-	-	•	•	•		4	0.0	Voltage phase L1 to L2
40110	U23	-	-	•	•	•		5	0.0	Voltage phase L2 to L3
40112	U31	-	-	•	•	•		6	0.0	Voltage phase L3 to L1
40114	UNE	-	-	-	-	•	7	0.0	Zero displacement voltage in 4-wire systems	
40116	I	•	-	•	-	-	REAL	0	0.0	System current
40118	I1	-	•	-	•	•		1	0.0	Current in phase L1
40120	I2	-	-	-	•	•		2	0.0	Current in phase L2
40122	I3	-	-	-	•	•		3	0.0	Current in phase L3
40124	IN	-	•	-	-	•		4	0.0	Neutral current
40126	IB	•	-	•	-	-		5	0.0	Bimetal current in balanced load systems
40128	IB1	-	•	-	•	•		6	0.0	Bimetal current in phase L 1
40130	IB2	-	•	-	•	•		7	0.0	Bimetal current in phase L2
40132	IB3	-	-	-	•	•	8	0.0	Bimetal current in phase L3	
40134	P	•	•	•	•	•	REAL	0	0.0	Active power system ($P = P1 + P2 + P3$)
40136	P1	-	•	-	-	•		1	0.0	Active power phase 1 (L1 – N)
40138	P2	-	•	-	-	•		2	0.0	Active power phase 2 (L2 – N)
40140	P3	-	-	-	-	•	3	0.0	Active power phase 3 (L3 – N)	
40142	Q	•	•	•	•	•	REAL	0	0.0	Reactive power system ($Q = Q1 + Q2 + Q3$)
40144	Q1	-	•	-	-	•		1	0.0	Reactive power phase 1 (L1 – N)
40146	Q2	-	•	-	-	•		2	0.0	Reactive power phase 2 (L2 – N)
40148	Q3	-	-	-	-	•	3	0.0	Reactive power phase 3 (L3 – N)	
40150	S	•	•	•	•	•	REAL	0	0.0	Apparent power system S
40152	S1	-	•	-	-	•		1	0.0	Apparent power phase 1 (L1 – N)
40154	S2	-	•	-	-	•		2	0.0	Apparent power phase 2 (L2 – N)
40156	S3	-	-	-	-	•	3	0.0	Apparent power phase 3 (L3 – N)	
40158	F	•	•	•	•	•	REAL	0	0.00	System frequency
40160	PF	•	•	•	•	•	REAL	0	0.0	$\cos(\varphi) = P / S$, Power factor system PF
40162	PF1	-	•	-	-	•		1	0.0	$\cos(\varphi)$ phase L1 (L1 – N)
40164	PF2	-	•	-	-	•		2	0.0	$\cos(\varphi)$ phase L2 (L2 – N)
40166	PF3	-	-	-	-	•	3	0.0	$\cos(\varphi)$ phase L3 (L3 – N)	
40168	QF	•	•	•	•	•	REAL	0	0.0	$\sin(\varphi) = Q / S$, Reactive power factor system QF
40170	QF1	-	•	-	-	•		1	0.0	$\sin(\varphi)$ phase L1 (L1 – N)
40172	QF2	-	•	-	-	•		2	0.0	$\sin(\varphi)$ phase L2 (L2 – N)
40174	QF3	-	-	-	-	•	3	0.0	$\sin(\varphi)$ phase L3 (L3 – N)	
40176	LF	•	•	•	•	•	REAL	0	0.0	$\text{sign}(Q) \cdot (1 - \text{abs}(\cos(\varphi)))$, Load factor system LF
40178	LF1	-	•	-	-	•		1	0.0	Load factor L1 (L1 – N)
40180	LF2	-	•	-	-	•		2	0.0	Load factor L2 (L2 – N)
40182	LF3	-	-	-	-	•	3	0.0	Load factor L3 (L3 – N)	
40184	U_MEAN	-	•	-	•	•	REAL	0	0.0	Average value of voltages $(U1N+U2N+U3N)/3$
40186	I_MEAN	-	•	-	•	•	REAL	1	0.0	Average value of currents $(I1+I2+I3)/3$

Modificat.	Date	Vis.:	Type: SINEAX CAM	Nr.: 11 / 34	author: 06.05.09 RR
			Description: Modbus/TCP interface	No: W 157471	

5.2 Instantaneous values of the harmonic analysis

Address	Name	14	2L	3G	3U	4U	Data type	#	Default	Description
40190	UNB_U	-	-	-	-	•	UINT16	0	0	Unbalance factor
40191	THD_U1X	U	U1N	U12	U12	U1N	UINT16	0	0	Total Harmonic Distortion
40192	THD_U2X	-	U2N	U23	U23	U2N		1	0	Total Harmonic Distortion
40193	THD_U3X	-	-	U31	U31	U3N		2	0	Total Harmonic Distortion
40194	TDD_I1	I	I1	I	I1	I1	UINT16	0	0	Total Demand Distortion
40195	TDD_I2	-	I2	-	I2	I2		1	0	Total Demand Distortion
40196	TDD_I3	-	-	-	I3	I3		2	0	Total Demand Distortion

These values are unsigned 16 bit numbers (1 quantity per register). 1000 corresponds to 100 %.

THD Harmonic content related to the fundamental of the RMS value of the voltage.

TDD Harmonic content related to the fundamental of the RMS value of the rated current.

5.3 Instantaneous values of the harmonics

Address	Name	14	2L	3G	3U	4U	Data type	#	Default	Description
40200	H2_U1X	U	U1N	U12	U12	U1N	UINT16	0	0	Content of the 2 nd voltage harmonic
	
40249	H50_U1X	-	U2N	U23	U23	U2N	UINT16	48	0	Content of the 50 th voltage harmonic
	
40298	H2_U2X	-	-	U31	U31	U3N	UINT16	0	0	Content of the 2 nd voltage harmonic
	
40347	H50_U2X	-	-	-	U31	U31	UINT16	48	0	Content of the 50 th voltage harmonic
	
40396	H2_U3X	I	I1	I	I1	I1	UINT16	0	0	Content of the 2 nd current harmonic
	
40445	H50_U3X	-	-	-	I3	I3	UINT16	48	0	Content of the 50 th current harmonic
	

These values are unsigned 16-Bit numbers (1 value per register). 1000 corresponds to 100 %.

Hi_UXX Harmonic content of the voltage related to the fundamental 100 %

Hi_IXX Harmonic content of the current converted to the rated current

Modificat.	Date	Vis.:	Type: SINEAX CAM	Nr.: 12 / 34	author: 06.05.09 RR
			Description: Modbus/TCP interface	No: W 157471	

5.4 Minimum / maximum values of system quantities

Time	Value	Reset coil	Name	Data type	#	Default	Description
40500	40584	500	U_MAX	TIME / REAL	0	1.1.2000 / 0.0	Maximum value U
40502	40586	501	U1N_MAX		1	1.1.2000 / 0.0	Maximum value U1N
40504	40588	502	U2N_MAX		2	1.1.2000 / 0.0	Maximum value U2N
40506	40590	503	U3N_MAX		3	1.1.2000 / 0.0	Maximum value U3N
40508	40592	504	U12_MAX		4	1.1.2000 / 0.0	Maximum value U12
40510	40594	505	U23_MAX		5	1.1.2000 / 0.0	Maximum value U23
40512	40596	506	U31_MAX		6	1.1.2000 / 0.0	Maximum value U31
40514	40598	507	UNE_MAX		7	1.1.2000 / 0.0	Maximum value UNE
40516	40600	508	I_MAX	TIME / REAL	0	1.1.2000 / 0.0	Maximum value I
40518	40602	509	I1_MAX		1	1.1.2000 / 0.0	Maximum value I1
40520	40604	510	I2_MAX		2	1.1.2000 / 0.0	Maximum value I2
40522	40606	511	I3_MAX		3	1.1.2000 / 0.0	Maximum value I3
40524	40608	512	IN_MAX		4	1.1.2000 / 0.0	Maximum value IN
40526	40610	513	IB_MAX		5	1.1.2000 / 0.0	Maximum value IB
40528	40612	514	IB1_MAX		6	1.1.2000 / 0.0	Maximum value IB1
40530	40614	515	IB2_MAX		7	1.1.2000 / 0.0	Maximum value IB2
40532	40616	516	IB3_MAX	8	1.1.2000 / 0.0	Maximum value IB3	
40534	40618	517	P_MAX	TIME / REAL	0	1.1.2000 / 0.0	Maximum value P
40536	40620	518	P1_MAX		1	1.1.2000 / 0.0	Maximum value P1
40538	40622	519	P2_MAX		2	1.1.2000 / 0.0	Maximum value P2
40540	40624	520	P3_MAX		3	1.1.2000 / 0.0	Maximum value P3
40542	40626	521	Q_MAX	TIME / REAL	0	1.1.2000 / 0.0	Maximum value Q
40544	40628	522	Q1_MAX		1	1.1.2000 / 0.0	Maximum value Q1
40546	40630	523	Q2_MAX		2	1.1.2000 / 0.0	Maximum value Q2
40548	40632	524	Q3_MAX		3	1.1.2000 / 0.0	Maximum value Q3
40550	40634	525	S_MAX	TIME / REAL	0	1.1.2000 / 0.0	Maximum value S
40552	40636	526	S1_MAX		1	1.1.2000 / 0.0	Maximum value S1
40554	40638	527	S2_MAX		2	1.1.2000 / 0.0	Maximum value S2
40556	40640	528	S3_MAX		3	1.1.2000 / 0.0	Maximum value S3
40558	40642	529	F_MAX	TIME / REAL		1.1.2000 / 0.0	Maximum value F
40560	40644	530	U_MIN	TIME / REAL	0	1.1.2000 / 0.0	Minimum value U
40562	40646	531	U1N_MIN		1	1.1.2000 / 0.0	Minimum value U1N
40564	40648	532	U2N_MIN		2	1.1.2000 / 0.0	Minimum value U2N
40566	40650	533	U3N_MIN		3	1.1.2000 / 0.0	Minimum value U3N
40568	40652	534	U12_MIN		4	1.1.2000 / 0.0	Minimum value U12
40570	40654	535	U23_MIN		5	1.1.2000 / 0.0	Minimum value U23
40572	40656	536	U31_MIN		6	1.1.2000 / 0.0	Minimum value U31
40574	40658	537	PF_MIN_IN_L		TIME / REAL	0	1.1.2000 / 0.0
40576	40660	538	PF_MIN_IN_C	1		1.1.2000 / 0.0	min. cos(φ) Inc./capacitive
40578	40662	539	PF_MIN_OUT_L	2		1.1.2000 / 0.0	min. cos(φ) Outg./inductive
40580	40664	540	PF_MIN_OUT_C	3		1.1.2000 / 0.0	min. cos(φ) Outg./capacitive
40582	40666	541	F_MIN	TIME / REAL		1.1.2000 / 75.	Minimum value of F

By setting Coil 500...541 (Reset) the appropriate maximum resp. minimum value with timestamp will be reset.

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			Description: Modbus/TCP interface	No: W 157471	

5.5 Maximum values of THD, TDD and harmonics

Register	Reset coil	Name	Data type	#	Default	Description
40670	670	UNB_U_TIME	TIME	0	1.1.2000	Time
40672		UNB_U_MAX	UINT16	0	0	max. unbalance factor
40673	671	H_U1X_TIME	TIME	0	1.1.2000	Time
40675		THD_U1X_MAX	UINT16	0	0	max. THD phase 1
		H2_U1X_MAX		1	0	max. content of 2nd voltage harmonic phase 1
	
		H50_U1X_MAX		49	0	max. content of 50th voltage harmonic phase 1
40725	672	H_U2X_TIME	TIME		1.1.2000	Time
40727		THD_U2X_MAX	UINT16	0	0	max. THD phase 3
		H2_U2X_MAX		1	0	max. content of 2nd voltage harmonic phase 2
	
		H50_U2X_MAX		49	0	max. content of 50th voltage harmonic phase 2
40777	673	H_U3X_TIME	TIME	0	1.1.2000	Time
40779		THD_U3X_MAX	UINT16	0	0	max. THD phase 3
		H2_U3X_MAX		1	0	max. content of 2nd voltage harmonic phase 3
	
		H50_U3X_MAX		49	0	max. content of 50th voltage harmonic phase 3
40829	674	H_I1X_TIME	TIME	0	1.1.2000	Time
40831		TDD_I1X_MAX	UINT16	0	0	max. THD phase 1
		H2_I1X_MAX		1	0	max. content of 2nd current harmonic phase 1
	
		H50_I1X_MAX		49	0	max. content of 50th current harmonic phase 1
40881	675	H_I2X_TIME	TIME	0	1.1.2000	Time
40883		TDD_I2X_MAX	UINT16	0	0	max. THD phase 2
		H2_I2X_MAX		1	0	max. content of 2nd current harmonic phase 2
	
		H50_I1X_MAX		49	0	max. content of 50th current harmonic phase 2
40933	676	H_I3X_TIME	TIME	0	1.1.2000	Time
40935		TDD_I3X_MAX	UINT16	0	0	max. THD phase 3
		H2_I3X_MAX		1	0	max. content of 2nd current harmonic phase 3
	
		H50_I3X_MAX		49	0	max. content of 50th current harmonic phase 3

These values are unsigned 16-Bit numbers (1 value per register). 1000 corresponds to 100 %.
By setting coils **670...676** the appropriate maximum values with timestamp will be reset.

Hi_UXX_MAX Harmonic content of the voltage related to the fundamental 100 %
Hi_IXX_MAX Harmonic content of the current related to the rated current

Modificat.	Date	Vis.:	Type: SINEAX CAM	Nr.: 14 / 34	author: 06.05.09 RR
			Description: Modbus/TCP interface	No: W 157471	

5.6 Mean values and trend with interval time t1

#	Mean val.	Trend	Maximum			Minimum		
NAME	REAL	REAL	TIME	REAL[value]	Reset	TIME	REAL [value]	Reset
AVG1.1	41030	41054	41078	41102	1030	41126	41150	1054
AVG1.2	41032	41056	41080	41104	1031	41128	41152	1055
AVG1.3	41034	41058	41082	41106	1032	41130	41154	1056
AVG1.4	41036	41060	41084	41108	1033	41132	41156	1057
AVG1.5	41038	41062	41086	41110	1034	41134	41158	1058
AVG1.6	41040	41064	41088	41112	1035	41136	41160	1059
AVG1.7	41042	41066	41090	41114	1036	41138	41162	1060
AVG1.8	41044	41068	41092	41116	1037	41140	41164	1061
AVG1.9	41046	41070	41094	41118	1038	41142	41166	1062
AVG1.10	41048	41072	41096	41120	1039	41144	41168	1063
AVG1.11	41050	41074	41098	41122	1040	41146	41170	1064
AVG1.12	41052	41076	41100	41124	1041	41148	41172	1065

5.7 Mean values and trend with interval time t2

#	Mean val.	Trend	Maximum			Minimum		
NAME	REAL	REAL	TIME	REAL[value]	Reset	TIME	REAL [value]	Reset
AVG2.1	41180	41204	41228	41252	1042	41276	41300	1066
AVG2.2	41182	41206	41230	41254	1043	41278	41302	1067
AVG2.3	41184	41208	41232	41256	1044	41280	41304	1068
AVG2.4	41186	41210	41234	41258	1045	41282	41306	1069
AVG2.5	41188	41212	41236	41260	1046	41284	41308	1070
AVG2.6	41190	41214	41238	41262	1047	41286	41310	1071
AVG2.7	41192	41216	41240	41264	1048	41288	41312	1072
AVG2.8	41194	41218	41242	41266	1049	41290	41314	1072
AVG2.9	41196	41220	41244	41268	1050	41292	41316	1074
AVG2.10	41198	41222	41246	41270	1051	41294	41318	1075
AVG2.11	41200	41224	41248	41272	1052	41296	41320	1076
AVG2.12	41202	41226	41250	41274	1053	41298	41322	1077

5.8 Instantaneous values of analog inputs

Address	Name	Data type	#	Default	Description
41330	AIN1	REAL	0	0	Analog input value 1.1
			1	0	Analog input value 1.2
41334	AIN2	REAL	0	0	Analog input value 2.1
			1	0	Analog input value 2.2
41338	AIN3	REAL	0	0	Analog input value 3.1
			1	0	Analog input value 3.2
41342	AIN4	REAL	0	0	Analog input value 4.1
			1	0	Analog input value 4.2

5.9 Instantaneous values of analog outputs

Address	Name	Data type	#	Default	Description
41362	AOUT1	UINT16	0	0	Analog output 1.1 16'384 corresponds to 100% of the hardware limit (20mA)
			1	0	Analog output 1.2 as 1.1
41364	AOUT2	UINT16	0	0	Analog output 2.1 as 1.1
			1	0	Analog output 2.2 as 1.1
41366	AOUT3	UINT16	0	0	Analog output 3.1 as 1.1
			1	0	Analog output 3.2 as 1.1
41368	AOUT4	UINT16	0	0	Analog output 4.1 as 1.1
			1	0	Analog output 4.2 as 1.1

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			Description: Modbus/TCP interface	No: W 157471	

5.10 Present state of limit values

Address	Name	Data type	#	Default	Description
42956	LIMIT_STATE	BYTE[8]	0	0	<u>Bit Meaning</u> 0 State of limit value 1 (0=OFF, 1=ON) 1 State of limit value 2 2 State of limit value 3 3 State of limit value 4 4 State of limit value 5 5 State of limit value 6 6 State of limit value 7 7 State of limit value 8
			1	0	As above, but state of limit value 9...16
			2	0	As above, but state of limit value 17...24
			3	0	As above, but state of limit value 25...32
			4	0	As above, but state of limit value 33...40
			5	0	As above, but state of limit value 41...48
			6	0	As above, but state of limit value 49...56
			7	0	As above, but state of limit value 57...64

5.11 Present state of logic functions

For all logic functions an initial value is defined. This initial value corresponds to the normal case, i.e. **no alarm or event not occurred**. If the result of the logic function (*LOGIC_FUNC*) is unlike the initial value, an exception is present, i.e. **alarm or event occurred**. In this case, delayed by a switch-in or dropout delay, an action is initiated. This is indicated by setting the corresponding bits in *LOGIC_STAT* and is independent of the state of the initial value.

If a logic function can be acknowledged, subsequent an action may be reset by a definable procedure, e.g. to switch off an alarm horn. Depending on the selected procedure this can be done for single logic functions or for all functions at the same time. So it's e.g. possible to selectively acknowledge functions by setting the appropriate bits in *LOGIC_RESET*. For which logic functions actions have been reset may be seen from the corresponding bits in *RESET_STAT*. If a bit is set, the associated logic function has been acknowledged.

Address	Name	Data type	#	Default	Description
43917	LOGIC_RESET	INT32	0	0	Acknowledge of alarms (events) - Write only <u>Bit corresponding function</u> 0 Logic function LS 1 1 Logic function LS 2 ... 30 Logic function LS 31 31 Logic function LS 32
43919	LOGIC_FUNC	UINT32	0	0	Present state of logic function LSx <i>Assignment as LOGIC_RESET</i>
43921	LOGIC_STAT	UINT32	0	0	State of alarm/event monitoring <i>Assignment as LOGIC_RESET</i>
43923	RESET_STAT	UINT32	0	0	Reset state of alarm/event monitoring <i>Assignment as LOGIC_RESET</i>

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			Description: Modbus/TCP interface	No: W 157471	

5.12 Present state of relays

Address	Name	Data type	#	Default	Description
1	RELAY1	COIL	0	0	State relay 1
2	RELAY2	COIL	0	0	State relay 2

5.13 Present state of digital I/Os

Address	Name	Data type	#	Default	Description
3	DIGIO1.1	COIL	0	0	State digital input / output 1.1
4	DIGIO1.2	COIL	0	0	State digital input / output 1.2
5	DIGIO1.3	COIL	0	0	State digital input / output 1.3
6	DIGIO2.1	COIL	0	0	State digital input / output 2.1
7	DIGIO2.2	COIL	0	0	State digital input / output 2.2
8	DIGIO2.3	COIL	0	0	State digital input / output 2.3
9	DIGIO3.1	COIL	0	0	State digital input / output 3.1
10	DIGIO3.2	COIL	0	0	State digital input / output 3.2
11	DIGIO3.3	COIL	0	0	State digital input / output 3.3
12	DIGIO4.1	COIL	0	0	State digital input / output 4.1
13	DIGIO4.2	COIL	0	0	State digital input / output 4.2
14	DIGIO4.3	COIL	0	0	State digital input / output 4.3

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			Description: Modbus/TCP interface	No: W 157471	

6. Meters

6.1 Tariff of meters

Address	Name	Data type	#	Default	Description
41025	CNT_TARIF	UINT16	0	0	Tariff situation (writable) <i>Value</i> <i>Meaning</i> 0 High tariff 1 Low tariff

6.2 Contents of the I/O meters

Value	Reset-Coil	Name	Data type	#	Default	Description
41400	1400	CNTR_AD_11	UINT32	0	0	Meter DIGIO / AIN 1.1 High tariff
41424	1412			1	0	Meter DIGIO / AIN 1.1 Low tariff
41402	1401	CNTR_AD_12	UINT32	0	0	Meter DIGIO / AIN 1.2 High tariff
41426	1413			1	0	Meter DIGIO / AIN 1.2 Low tariff
41404	1402	CNTR_D_13	UINT32	0	0	Meter DIGIO 1.3 High tariff
41428	1414			1	0	Meter DIGIO 1.3 Low tariff
41406	1403	CNTR_AD_21	UINT32	0	0	Meter DIGIO / AIN 2.1 High tariff
41430	1415			1	0	Meter DIGIO / AIN 2.1 Low tariff
41408	1404	CNTR_AD_22	UINT32	0	0	Meter DIGIO / AIN 2.2 High tariff
41432	1416			1	0	Meter DIGIO / AIN 2.2 Low tariff
41410	1405	CNTR_D_23	UINT32	0	0	Meter DIGIO 2.3 High tariff
41434	1417			1	0	Meter DIGIO 2.3 Low tariff
41412	1406	CNTR_AD_31	UINT32	0	0	Meter DIGIO / AIN 3.1 High tariff
41436	1418			1	0	Meter DIGIO / AIN 3.1 Low tariff
41414	1407	CNTR_AD_32	UINT32	0	0	Meter DIGIO / AIN 3.2 High tariff
41438	1419			1	0	Meter DIGIO / AIN 3.2 Low tariff
41416	1408	CNTR_D_33	UINT32	0	0	Meter DIGIO 3.3 High tariff
41440	1420			1	0	Meter DIGIO 3.3 Low tariff
41418	1409	CNTR_D_41	UINT32	0	0	Meter DIGIO / AIN 4.1 High tariff
41442	1421			1	0	Meter DIGIO / AIN 4.1 Low tariff
41420	1410	CNTR_D_42	UINT32	0	0	Meter DIGIO / AIN 4.2 High tariff
41444	1422			1	0	Meter DIGIO / AIN 4.2 Low tariff
41422	1411	CNTR_D_43	UINT32	0	0	Meter DIGIO 4.3 High tariff
41446	1423			1	0	Meter DIGIO 4.3 Low tariff

By setting Coil 1400...1423 the appropriate meter will be reset.

6.3 Scaling factors of the I/O meters

Value	Name	Data type	#	Default	Description
41448	CNTR_EXP_AD_11	UINT16	0	0	Scaling factor DIGIO / AIN 1.1
41449	CNTR_EXP_AD_12	UINT16	0	0	Scaling factor DIGIO / AIN 1.2
41450	CNTR_EXP_D_13	UINT16	0	0	Scaling factor DIGIO 1.3
41451	CNTR_EXP_AD_21	UINT16	0	0	Scaling factor DIGIO / AIN 2.1
41452	CNTR_EXP_AD_22	UINT16	0	0	Scaling factor DIGIO / AIN 2.2
41453	CNTR_EXP_D_23	UINT16	0	0	Scaling factor DIGIO 2.3
41454	CNTR_EXP_AD_31	UINT16	0	0	Scaling factor DIGIO / AIN 3.1
41455	CNTR_EXP_AD_32	UINT16	0	0	Scaling factor DIGIO / AIN 3.2
41456	CNTR_EXP_D_33	UINT16	0	0	Scaling factor DIGIO 3.3
41457	CNTR_EXP_D_41	UINT16	0	0	Scaling factor DIGIO / AIN 4.1
41458	CNTR_EXP_D_42	UINT16	0	0	Scaling factor DIGIO / AIN 4.2
41459	CNTR_EXP_D_43	UINT16	0	0	Scaling factor DIGIO 4.3

The units of the meters can be derived from the unit of the corresponding inputs.

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			Description: Modbus/TCP interface	No: W 157471	

7. Parameters and settings

7.1 Security system

Address	Name	Data type	#	Default	Description
42020	WR_PROTECT	UINT16	0	0x5AA5	Write protection <i>Value Meaning</i> 0x5AA5 inactive 0xA55A active
42021	USR_RIGHTS	UINT16	0	0	Access rights user 1 <i>Bit Meaning Bit Description</i> 0 Configuration 6 Manipulation lists 1 Real time clock 7 Disturbance recorder 2 Limit values 8 Adjustment analog inputs 3 Min / Max values 9 Simulations 4 Meter, Tariff situation 10 Alarm acknowledgement 5 Manipulation logger
42022			1	0	Access rights user 2 (as user 1)
42023			2	0	Access rights user 3 (as user 1)
42024	PW_ADMIN	CHAR[20]	0	„admin“	Encoded Password administrator
42034	PW_USERS	CHAR[20]	0	„user1“	User identification user 1
42044			1	„user1“	Password user 1
42054			2	„user2“	User identification user 2
42064			3	„user2“	Password user 2
42074			4	„user3“	User identification user 3
42084			5	„user3“	Password user 3
42094	ACTIV_CFG	UINT16	0	0	active parameter set

7.2 General parameters

Address	Name	Data type	#	Default	Description
42095	DEV_DESC	CHAR[48]	0	„CAM“	Device description
42119	DEV_STATUS	UINT16	0	0	Device status
42120	DEV_TEMP	UINT16	0	0	Device temperature
42121	DEV_USER	UINT16	0	0	User (0: device, 1: admin, 2: user 1, 3: user 2, 4: user 3)

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			Description: Modbus/TCP interface	No: W 157471	

7.3 Parameters of the measurement input

Address	Name	Data type	#	Default	Description
42200	INPUT_CFG	UINT8	0	0x04	System <i>Value Meaning</i> 0x00 Single phase 0x05 Split phase 0x01 3-wire, balanced load 0x11 3-wire, balanced load, U = U12 0x21 3-wire, balanced load, U = U23 0x31 3-wire, balanced load, U = U31 0x13 3-wire, unbalanced load 0x03 3-wire, unbalanced load, Aron 0x02 4-wire, balanced load 0x04 4-wire, unbalanced load 0x14 4-wire, unbalanced load, Open-Y
			1	0x04	Settings <i>Bit Meaning 0 1</i> 0, 1 Freq. measurement via 0 Voltage 1 Current 2 Automatic 2 Sampling freq. adaptive fixed 3 Rotation sense left-hand right-hand 4 Quadrants electrical mathematical 5 Input measurement normal interrupted 6 Frequency meas. filtered fast
42201	MAIN_FREQ	UINT16	0	5000	Rated frequency in 1/100 Hz
42202	IN_VOLTAGE	REAL	0	110.0	Rated voltage primary (L-L)
42204			1	110.0	Rated voltage secondary (L-L)
42206	IN_CURRENT	REAL	0	1.0	Rated current primary
42208			1	1.0	Rated current secondary
42210	IN_VOLT_MAX	REAL	0	132.0	Maximum voltage secondary (L-L)
42212	IN_CURR_MAX	REAL	0	1.2	Maximum current secondary
42214	EFF_MEAN_TP	UINT16	0	1	RMS averaging over 2, 3, 4, 8, 16, 32, 64, 128...1024 cycles
42215	IB_MEAN_TP	UINT16	0	15	Low-pass time constant for bimetal current [min]

Modificat.	Date	Vis.:	Type: SINEAX CAM	Nr.: 21 / 34	author: 06.05.09 RR
			Description: Modbus/TCP interface	No: W 157471	

7.4 Parameters of mean values

Address	Name	Data type	#	Default	Description																																																																																																																																																							
42600	MEAN_BAS_T1	UINT16[12]	0	[0,0,0...	<p>Base of the 12 measurements for interval time t1</p> <table border="1"> <thead> <tr> <th>Value</th> <th>Meaning</th> </tr> </thead> <tbody> <tr><td>0</td><td>not used</td></tr> <tr><td>1</td><td>General instantaneous values</td></tr> <tr><td>2</td><td>THD, TDD</td></tr> <tr><td>16</td><td>analog inputs AIN</td></tr> <tr><td>19</td><td>digital inputs with HT (DIH) and LT(DIL)</td></tr> </tbody> </table>	Value	Meaning	0	not used	1	General instantaneous values	2	THD, TDD	16	analog inputs AIN	19	digital inputs with HT (DIH) and LT(DIL)																																																																																																																																											
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42612	MEAN_IND_T1	UINT16[12]	0	[0,0,0...	<p>Index of the 12 measurements for interval time t1</p> <table border="1"> <thead> <tr> <th rowspan="2">Index</th> <th colspan="4">Base</th> </tr> <tr> <th>1</th> <th>2</th> <th>16</th> <th>19</th> </tr> </thead> <tbody> <tr><td>0</td><td>U</td><td>UNB_U</td><td>AIN1.1</td><td>DIH1.1</td></tr> <tr><td>1</td><td>U1N</td><td>THD_U1X</td><td>AIN1.2</td><td>DIH1.2</td></tr> <tr><td>2</td><td>U2N</td><td>THD_U2X</td><td>AIN2.1</td><td>DIH1.3</td></tr> <tr><td>3</td><td>U3N</td><td>THD_U3X</td><td>AIN2.2</td><td>DIH2.1</td></tr> <tr><td>4</td><td>U12</td><td>TDD_11X</td><td>AIN3.1</td><td>DIH2.2</td></tr> <tr><td>5</td><td>U23</td><td>TDD_12X</td><td>AIN3.2</td><td>DIH2.3</td></tr> <tr><td>6</td><td>U31</td><td>TDD_13X</td><td>AIN4.1</td><td>DIH3.1</td></tr> <tr><td>7</td><td>UNE</td><td></td><td>AIN4.2</td><td>DIH3.2</td></tr> <tr><td>8</td><td>I</td><td></td><td></td><td>DIH3.3</td></tr> <tr><td>9</td><td>I1</td><td></td><td></td><td>DIH4.1</td></tr> <tr><td>10</td><td>I2</td><td></td><td></td><td>DIH4.2</td></tr> <tr><td>11</td><td>I3</td><td colspan="3">Meter DIGIN4.3 High tariff =</td><td>DIH4.3</td></tr> <tr><td>12</td><td>IN</td><td></td><td></td><td>DIL1.1</td></tr> <tr><td>13</td><td>IB</td><td></td><td></td><td>DIL1.2</td></tr> <tr><td>14</td><td>IB1</td><td></td><td></td><td>DIL1.3</td></tr> <tr><td>15</td><td>IB2</td><td></td><td></td><td>DIL2.1</td></tr> <tr><td>16</td><td>IB3</td><td></td><td></td><td>DIL2.2</td></tr> <tr><td>17</td><td>P</td><td></td><td></td><td>DIL2.3</td></tr> <tr><td>18</td><td>P1</td><td></td><td></td><td>DIL3.1</td></tr> <tr><td>19</td><td>P2</td><td></td><td></td><td>DIL3.2</td></tr> <tr><td>20</td><td>P3</td><td></td><td></td><td>DIL3.3</td></tr> <tr><td>21</td><td>Q</td><td></td><td></td><td>DIL4.1</td></tr> <tr><td>22</td><td>Q1</td><td></td><td></td><td>DIL4.2</td></tr> <tr><td>23</td><td>Q2</td><td colspan="3">Meter DIGIN4.3 Low tariff =</td><td>DIL4.3</td></tr> <tr><td>24</td><td>Q3</td><td></td><td></td><td></td></tr> <tr><td>25</td><td>S</td><td></td><td></td><td></td></tr> <tr><td>...</td><td>...</td><td></td><td></td><td></td></tr> <tr><td>43</td><td>Imean</td><td></td><td></td><td></td></tr> </tbody> </table> <p>etc. (see table general instantaneous values)</p> <p>For base 1 and 16 (Data type real) the index must be multiplied by 2.</p>	Index	Base				1	2	16	19	0	U	UNB_U	AIN1.1	DIH1.1	1	U1N	THD_U1X	AIN1.2	DIH1.2	2	U2N	THD_U2X	AIN2.1	DIH1.3	3	U3N	THD_U3X	AIN2.2	DIH2.1	4	U12	TDD_11X	AIN3.1	DIH2.2	5	U23	TDD_12X	AIN3.2	DIH2.3	6	U31	TDD_13X	AIN4.1	DIH3.1	7	UNE		AIN4.2	DIH3.2	8	I			DIH3.3	9	I1			DIH4.1	10	I2			DIH4.2	11	I3	Meter DIGIN4.3 High tariff =			DIH4.3	12	IN			DIL1.1	13	IB			DIL1.2	14	IB1			DIL1.3	15	IB2			DIL2.1	16	IB3			DIL2.2	17	P			DIL2.3	18	P1			DIL3.1	19	P2			DIL3.2	20	P3			DIL3.3	21	Q			DIL4.1	22	Q1			DIL4.2	23	Q2	Meter DIGIN4.3 Low tariff =			DIL4.3	24	Q3				25	S							43	Imean			
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42624	MEAN_ATT_T1	CHAR[12]	0	[0,0,0...	<p>Attributes of mean values</p> <table border="1"> <tr> <td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> <tr> <td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td> </tr> <tr> <td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td> </tr> <tr> <td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td> </tr> <tr> <td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td> </tr> <tr> <td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td> </tr> <tr> <td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td> </tr> <tr> <td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td> </tr> <tr> <td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td> </tr> <tr> <td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td> </tr> <tr> <td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td> </tr> <tr> <td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td> </tr> <tr> <td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td> </tr> </table> <p>Incoming Outgoing Inductive Capacitive</p>	7	6	5	4	3	2	1	0																																																																																																																																															
7	6	5	4	3	2	1	0																																																																																																																																																					
42630	MEAN_SYN_T1	UINT16	0	0	<p>Synchronization of interval</p> <table border="1"> <thead> <tr> <th>Value</th> <th>Meaning</th> </tr> </thead> <tbody> <tr><td>0</td><td>without</td></tr> <tr><td>1</td><td>via digital input 1.1</td></tr> <tr><td>2</td><td>via digital input 1.2</td></tr> </tbody> </table> <p>etc.</p>	Value	Meaning	0	without	1	via digital input 1.1	2	via digital input 1.2																																																																																																																																															
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42631	MEAN_INT_T1	UINT16	0	900	time interval t1 in seconds																																																																																																																																																							
42632	MEAN_BAS_T2	UINT16[12]	0	[0,0,0...	Base of 12 measurements with interval time t2 (see 42600)																																																																																																																																																							
42644	MEAN_OFF_T2	UINT16[12]	0	[0,0,0...	Index of 12 measurements for interval time t2 (see 42612)																																																																																																																																																							
42656	MEAN_ATT_T2	UINT16[12]	0	[0,0,0...	Attributes of mean values (see 42624)																																																																																																																																																							
42662	MEAN_SYN_T2	UINT16	0	0	Synchronization of interval (see 42630)																																																																																																																																																							
42663	MEAN_INT_T2	UINT16	0	900	time interval t2 in seconds																																																																																																																																																							

7.5 Parameters of limit values

Address	Name	Data type	Default	Description																																																																																																																																																																														
42700	LIMIT_BASE	UINT16[64]	0	Base of the measurand <i>value meaning</i> 0 not used 1 general instantaneous values 2 THD, TDD 13 t1: mean values MEAN1 / Trend mean values TRM1 14 t2: mean values MEAN2 / Trend mean values TRM2 16 analog inputs AIN																																																																																																																																																																														
42764	LIMIT_OFFSET	UINT16[64]	0	Index of the measurand <i>Base</i> <table border="1"> <thead> <tr> <th>Index</th> <th>1</th> <th>2</th> <th>13</th> <th>14</th> <th>16</th> </tr> </thead> <tbody> <tr><td>0</td><td>U</td><td>UNB_U</td><td>MEAN1_1</td><td>MEAN2_1</td><td>AIN1.1</td></tr> <tr><td>2</td><td>U1N</td><td>THD_U1X</td><td>MEAN1_2</td><td>MEAN2_2</td><td>AIN1.2</td></tr> <tr><td>4</td><td>U2N</td><td>THD_U2X</td><td>MEAN1_3</td><td>MEAN2_3</td><td>AIN2.1</td></tr> <tr><td>6</td><td>U3N</td><td>THD_U3X</td><td>MEAN1_4</td><td>MEAN2_4</td><td>AIN2.2</td></tr> <tr><td>8</td><td>U12</td><td>TDD_I1X</td><td>MEAN1_5</td><td>MEAN2_5</td><td>AIN3.1</td></tr> <tr><td>10</td><td>U23</td><td>TDD_I2X</td><td>MEAN1_6</td><td>MEAN2_6</td><td>AIN3.2</td></tr> <tr><td>12</td><td>U31</td><td>TDD_I3X</td><td>MEAN1_7</td><td>MEAN2_7</td><td>AIN4.1</td></tr> <tr><td>14</td><td>UNE</td><td></td><td>MEAN1_8</td><td>MEAN2_8</td><td>AIN4.2</td></tr> <tr><td>16</td><td>I</td><td></td><td>MEAN1_9</td><td>MEAN2_9</td><td></td></tr> <tr><td>18</td><td>I1</td><td></td><td>MEAN1_10</td><td>MEAN2_10</td><td></td></tr> <tr><td>20</td><td>I2</td><td></td><td>MEAN1_11</td><td>MEAN2_11</td><td></td></tr> <tr><td>22</td><td>I3</td><td></td><td>MEAN1_12</td><td>MEAN2_12</td><td></td></tr> <tr><td>24</td><td>IN</td><td></td><td>TRM1_1</td><td>TRM2_1</td><td></td></tr> <tr><td>26</td><td>IB</td><td></td><td>TRM1_2</td><td>TRM2_2</td><td></td></tr> <tr><td>28</td><td>IB1</td><td></td><td>TRM1_3</td><td>TRM2_3</td><td></td></tr> <tr><td>30</td><td>IB2</td><td></td><td>TRM1_4</td><td>TRM2_4</td><td></td></tr> <tr><td>32</td><td>IB3</td><td></td><td>TRM1_5</td><td>TRM2_5</td><td></td></tr> <tr><td>34</td><td>P</td><td></td><td>TRM1_6</td><td>TRM2_6</td><td></td></tr> <tr><td>36</td><td>P1</td><td></td><td>TRM1_7</td><td>TRM2_7</td><td></td></tr> <tr><td>38</td><td>P2</td><td></td><td>TRM1_8</td><td>TRM2_8</td><td></td></tr> <tr><td>40</td><td>P3</td><td></td><td>TRM1_9</td><td>TRM2_9</td><td></td></tr> <tr><td>42</td><td>Q</td><td></td><td>TRM1_10</td><td>TRM2_10</td><td></td></tr> <tr><td>44</td><td>Q1</td><td></td><td>TRM1_11</td><td>TRM2_11</td><td></td></tr> <tr><td>46</td><td>Q2</td><td></td><td>TRM1_12</td><td>TRM2_12</td><td></td></tr> <tr><td>48</td><td>Q3</td><td></td><td></td><td></td><td></td></tr> <tr><td>50</td><td>S</td><td></td><td></td><td></td><td></td></tr> <tr><td>...</td><td>...</td><td></td><td></td><td></td><td></td></tr> <tr><td>86</td><td>Imean</td><td></td><td></td><td></td><td></td></tr> </tbody> </table> (see table general instantaneous values) For base 2 the index must be divided by 2.	Index	1	2	13	14	16	0	U	UNB_U	MEAN1_1	MEAN2_1	AIN1.1	2	U1N	THD_U1X	MEAN1_2	MEAN2_2	AIN1.2	4	U2N	THD_U2X	MEAN1_3	MEAN2_3	AIN2.1	6	U3N	THD_U3X	MEAN1_4	MEAN2_4	AIN2.2	8	U12	TDD_I1X	MEAN1_5	MEAN2_5	AIN3.1	10	U23	TDD_I2X	MEAN1_6	MEAN2_6	AIN3.2	12	U31	TDD_I3X	MEAN1_7	MEAN2_7	AIN4.1	14	UNE		MEAN1_8	MEAN2_8	AIN4.2	16	I		MEAN1_9	MEAN2_9		18	I1		MEAN1_10	MEAN2_10		20	I2		MEAN1_11	MEAN2_11		22	I3		MEAN1_12	MEAN2_12		24	IN		TRM1_1	TRM2_1		26	IB		TRM1_2	TRM2_2		28	IB1		TRM1_3	TRM2_3		30	IB2		TRM1_4	TRM2_4		32	IB3		TRM1_5	TRM2_5		34	P		TRM1_6	TRM2_6		36	P1		TRM1_7	TRM2_7		38	P2		TRM1_8	TRM2_8		40	P3		TRM1_9	TRM2_9		42	Q		TRM1_10	TRM2_10		44	Q1		TRM1_11	TRM2_11		46	Q2		TRM1_12	TRM2_12		48	Q3					50	S									86	Imean				
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86	Imean																																																																																																																																																																																	
42828	LIMIT_ON	INT[64]	0	Limit values for state ON Related to the configured maximum value of the measurand (100% = 16'384)																																																																																																																																																																														
42892	LIMIT_OFF	INT[64]	0	Limit values for state OFF Related to the configured maximum value of the measurand (100% = 16'384)																																																																																																																																																																														

- Upper limit value (monitoring of a rise over a limit value): $LIMIT_ON > LIMIT_OFF$
- Lower limit value (monitoring of a fall below a limit value): $LIMIT_ON < LIMIT_OFF$
- Hysteresis corresponds to the difference between LIMIT_ON and LIMIT_OFF

Example:

Rated current 100/1A with 50% over range, $I_1 > 120A$ should be monitored, hysteresis 5A

100% = 16'384 is related to 150A (100A +50%)

▶ $LIMIT_ON = 16'384 \times 120 / 150 = 13'107$

▶ $LIMIT_OFF = 16'384 \times (120-5) / 150 = 12'561$

Modificat.	Date	Vis.:	Type: SINEAX CAM	Nr.: 23 / 34	author: 06.05.09 RR
			Description: Modbus/TCP interface	No: W 157471	

7.6 Parameters of the real time clock

Address	Name	Data type	Default	Description																		
41550	RTC_TIME	TIME	0	UTC time in seconds since 1st of January 1970, Date range: 1.1.2005 ...																		
41552	EV_TIME	UINT32	0	UTC time of last event																		
41554	RTC_SYNC	UINT16	0	Synchronization <table border="0"> <thead> <tr> <th><i>Bit</i></th> <th><i>Meaning</i></th> </tr> </thead> <tbody> <tr> <td>0</td> <td>no synchronization</td> </tr> <tr> <td>1</td> <td>via measurement input</td> </tr> <tr> <td>2</td> <td>via HV input</td> </tr> <tr> <td>3, 4, 5</td> <td>via digital input 1.1 / 1.2 / 1.3</td> </tr> <tr> <td>6, 7, 8</td> <td>via digital input 2.1 / 2.2 / 2.3</td> </tr> <tr> <td>9, 10, 11</td> <td>via digital input 3.1 / 3.2 / 3.3</td> </tr> <tr> <td>12, 13, 14</td> <td>via digital input 4.1 / 4.2 / 4.3</td> </tr> <tr> <td>15</td> <td>via time server (Bus card)</td> </tr> </tbody> </table>	<i>Bit</i>	<i>Meaning</i>	0	no synchronization	1	via measurement input	2	via HV input	3, 4, 5	via digital input 1.1 / 1.2 / 1.3	6, 7, 8	via digital input 2.1 / 2.2 / 2.3	9, 10, 11	via digital input 3.1 / 3.2 / 3.3	12, 13, 14	via digital input 4.1 / 4.2 / 4.3	15	via time server (Bus card)
<i>Bit</i>	<i>Meaning</i>																					
0	no synchronization																					
1	via measurement input																					
2	via HV input																					
3, 4, 5	via digital input 1.1 / 1.2 / 1.3																					
6, 7, 8	via digital input 2.1 / 2.2 / 2.3																					
9, 10, 11	via digital input 3.1 / 3.2 / 3.3																					
12, 13, 14	via digital input 4.1 / 4.2 / 4.3																					
15	via time server (Bus card)																					
41555	RTC_INTERVAL	UINT32	0	Synchronization interval [s] for external time emitter																		
41557	RTC_AJUST	REAL	0	Clock adjustment in seconds per day + Clock is too slow - Clock goes ahead																		
41559	OPERATION_TIME	UINT32	0	Operating hours counter [h]																		
41561	NTP_UPDATE	UINT32	0	UTC time of last time synchronization via NTP																		

Setting the clock

Special care must be taken when putting the clock back. Present logger or list data may lie then in the future. The same happens if for test purposes the time is put forward and then back again.

In both cases no new data will be logged until the time of the last event is reached again.

7.7 Parameters of the Ethernet bus card

Address	Name	Data type	#	Default	Description
44900	TCP_IP	UINT8[4]	0	101	IP address of the Ethernet card (default: 192.168.1.101)
			1	1	
			2	168	
			3	192	
44902	TCP_SUBNET	UINT8[4]	0	255.255.255.0	Subnet mask
44904	TCP_GATEWAY	UINT8[4]	0	192.168.1.1	Gateway address
44906	TCP_NTP1	UINT8[4]	0	0.0.0.0	IP address NTP server 1
44908	TCP_NTP2	UINT8[4]	0	0.0.0.0	IP address NTP server 2
44910	TCP_PORT	UINT16	0	502	Alternative Modbus/TCP port

Modificat.	Date	Vis.:	Type: SINEAX CAM	Nr.: 24 / 34	author: 06.05.09 RR
			Description: Modbus/TCP interface	No: W 157471	

7.8 Parameters of the analog inputs

Address	Name	Data type	#	Default	Description
42420	AIN1.1	UINT16	0	0	<u>Unit</u>
		INT16	0	0	Trimming Gain $\pm 16'384 = \pm 20\text{mA}$
		INT16	0	0	Trimming Offset $\pm 16'384 = \pm 20\text{mA}$
		INT16	0	0	Input values for 0% (100% = 16'384)
			1	16'384	Input value for 100%
		REAL	0	0	Physical value for 0%
			1	16'384	Physical value for 100%
		UINT16	0	0	time constant input low-pass filter [0...5000] in 1/100 s
42430	AIN1.2				Analog input 1.2 as 1.1
42440	AIN2.1		0	0	Analog input 2.1 as 1.1
42450	AIN2.2		1	0	Analog input 2.2 as 1.1
42460	AIN3.1		0	0	Analog input 3.1 as 1.1
42470	AIN3.2		1	0	Analog input 3.2 as 1.1
42480	AIN4.1		0	0	Analog input 4.1 as 1.1
42490	AIN4.2		1	0	Analog input 4.2 as 1.1

7.9 Parameters of the digital inputs

Address	Name	Data type	#	Default	Description													
42420	DIGIO1.1	UINT16	0	0	<u>Unit</u>													
		UINT32	0	0	Number of pulses per energy unit													
		UINT32	0	0	reserved													
		UINT8	0	100	Minimum pulse length in ms													
			1	0	<table border="1"> <thead> <tr> <th>Bit</th> <th>Meaning</th> <th>0</th> <th>1</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>Signal types</td> <td>state</td> <td>Edge</td> </tr> <tr> <td>1</td> <td>Polarity</td> <td>falling</td> <td>rising</td> </tr> <tr> <td>2</td> <td>Tariff switching</td> <td>OFF</td> <td>ON</td> </tr> </tbody> </table>	Bit	Meaning	0	1	0	Signal types	state	Edge	1	Polarity	falling	rising	2
Bit	Meaning	0	1															
0	Signal types	state	Edge															
1	Polarity	falling	rising															
2	Tariff switching	OFF	ON															
42426	DIGIO1.2				Digital input 1.2 as 1.1													
42432	DIGIO1.3				Digital input 1.3 as 1.1													
42440	DIGIO2.1		0		Digital input 2.1 as 1.1													
42446	DIGIO2.2		1		Digital input 2.2 as 1.1													
42452	DIGIO2.3		2		Digital input 2.3 as 1.1													
42460	DIGIO3.1		0		Digital input 3.1 as 1.1													
42466	DIGIO3.2		1		Digital input 3.2 as 1.1													
42472	DIGIO3.3		2		Digital input 3.3 as 1.1													
42480	DIGIO4.1		0		Digital input 4.1 as 1.1													
42486	DIGIO4.2		1		Digital input 4.2 as 1.1													
42492	DIGIO4.3		2		Digital input 4.3 as 1.1													

7.10 Parameters of the HV module (always module 4)

Address	Name	Data type	#	Default	Description							
42480	HVIN	UINT16	0	0	<u>Unit</u>							
		UINT32	0	0	Number of pulses per energy unit							
		UINT32	0	0	reserved							
		UINT8	0	100	Minimum pulse length in ms							
			1		<table border="1"> <thead> <tr> <th>Bit</th> <th>Meaning</th> <th>0</th> <th>1</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>Signal types</td> <td>state</td> <td>Edge</td> </tr> </tbody> </table>	Bit	Meaning	0	1	0	Signal types	state
		Bit	Meaning	0	1							
0	Signal types	state	Edge									
UINT16	0	5000	Synchronization rated frequency in 1/100 Hz									

Modificat.	Date	Vis.:	Type: SINEAX CAM	Nr.: 25 / 34	author: 06.05.09 RR
			Description: Modbus/TCP interface	No: W 157471	

8. Simulation mode

The simulation mode allows simulating the values of analog / digital outputs or the states of logical functions of the logic module. It's intended for testing of subsequent circuits during commissioning.

There are two possibilities to stop the simulation mode:

- Setting the register SIM_MOD to 0
- Switching off the auxiliary power

Address	Name	Data type	Default	Description
41600	SIM_MOD	UINT16	0	Simulation mode (0 = OFF) <i>Bit meaning</i> 0 not used 1 Logic functions 2 Analog outputs 3 Digital outputs + Relays
41601	SIM_OUT1	UINT16	0	Bit mask for simulation (see below)
41602	SIM_OUT2	UINT16	0	Bit mask for simulation (see below)

8.1 Simulation of digital outputs and relay states

Start:

Address	Name	Value
41600	SIM_MOD	8
41601	SIM_OUT1	<p>Which digital output channels should be simulated ?</p>
41602	SIM_OUT2	Not used

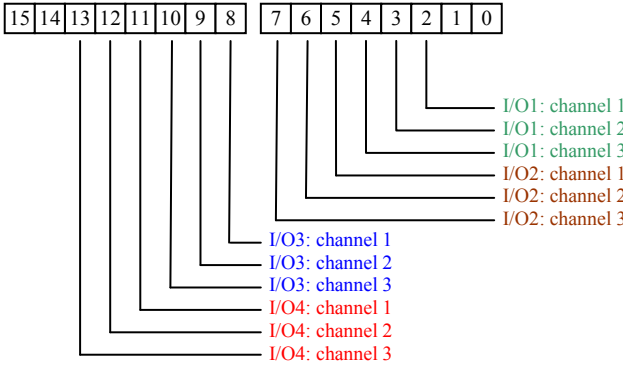
Setting states: For all selected channels in SIM_OUT1 a state can be simulated

Address	Name	Data type	Dedicated digital output
1	RELAY1	COIL	State relay 1
2	RELAY2	COIL	State relay 2
3	DIGIO1.1	COIL	State digital output I/O1.1
4	DIGIO1.2	COIL	State digital output I/O1.2
5	DIGIO1.3	COIL	State digital output I/O1.3
6	DIGIO2.1	COIL	State digital output I/O2.1
7	DIGIO2.2	COIL	State digital output I/O2.2
8	DIGIO2.3	COIL	State digital output I/O2.3
9	DIGIO3.1	COIL	State digital output I/O3.1
10	DIGIO3.2	COIL	State digital output I/O3.2
11	DIGIO3.3	COIL	State digital output I/O3.3
12	DIGIO4.1	COIL	State digital output I/O4.1
13	DIGIO4.2	COIL	State digital output I/O4.2
14	DIGIO4.3	COIL	State digital output I/O4.3

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			Description: Modbus/TCP interface	No: W 157471	

8.2 Simulation of analog outputs

Start:

Address	Name	Value
41600	SIM_MOD	4
41601	SIM_OUT1	<p>Which analog output channels should be simulated ?</p> 
41602	SIM_OUT2	Not used

Setting output values: For all selected channels in SIM_OUT1 a value can be simulated

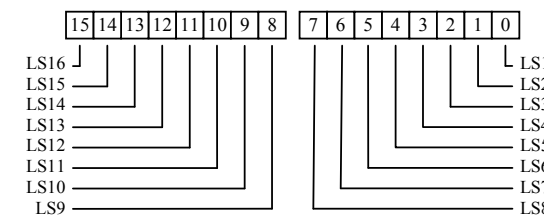
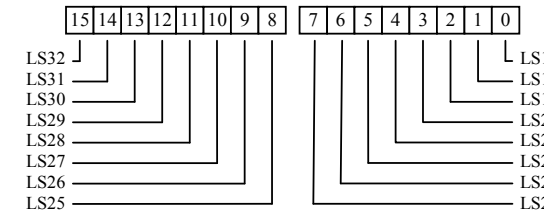
Address	Name	Data type	Dedicated analog output
41362	AOUT1	UINT16	Analog output I/O1.1
41363			Analog output I/O1.2
41364	AOUT2	UINT16	Analog output I/O2.1
41365			Analog output I/O2.2
41366	AOUT3	UINT16	Analog output I/O3.1
41367			Analog output I/O3.2
41368	AOUT4	UINT16	Analog output I/O4.1
41369			Analog output I/O4.2

16'384 corresponds to 100% of the **hardware** upper range limit (20mA).

8.3 Simulation of logic functions

These will work starting from firmware version 1.06 of the analysis part and CB-Manager version 1.03

Start:

Address	Name	Value
41600	SIM_MOD	2
41601	SIM_OUT1	<p>Which logic functions should be simulated ?</p> 
41602	SIM_OUT2	<p>Which logic functions should be simulated ?</p> 

Logic functions not used in the logic module can't be simulated.

Modificat.	Date	Vis.:	Type: SINEAX CAM	Nr.: 29 / 34	author: 06.05.09 RR
			Description: Modbus/TCP interface	No: W 157471	

Setting logical states: For all selected channels in SIM_OUT1 or SIM_OUT2 a state can be simulated

Address	Name	Data type	Value
43919	LOGIC_FUNC1	UINT16	Value of logic functions LS1...LS16
43920	LOGIC_FUNC2	UINT16	Value of logic functions LS17...LS32

9. Remote I/O

The Modbus master can use all relays or digital outputs which **haven't been used** for the device functionality for own purposes.

This feature is supported starting from version 1.06 of the analysis part.

Address	Name	Data type	Dedicated digital output
1	RELAY1	COIL	State relay 1
2	RELAY2	COIL	State relay 2
3	DIGIO1.1	COIL	State digital output I/O1.1
4	DIGIO1.2	COIL	State digital output I/O1.2
5	DIGIO1.3	COIL	State digital output I/O1.3
6	DIGIO2.1	COIL	State digital output I/O2.1
7	DIGIO2.2	COIL	State digital output I/O2.2
8	DIGIO2.3	COIL	State digital output I/O2.3
9	DIGIO3.1	COIL	State digital output I/O3.1
10	DIGIO3.2	COIL	State digital output I/O3.2
11	DIGIO3.3	COIL	State digital output I/O3.3
12	DIGIO4.1	COIL	State digital output I/O4.1
13	DIGIO4.2	COIL	State digital output I/O4.2
14	DIGIO4.3	COIL	State digital output I/O4.3

Modificat.	Date	Vis.:	Type: SINEAX CAM	Nr.: 30 / 34	author: 06.05.09 RR
			Description: Modbus/TCP interface	No: W 157471	

APPENDIX A

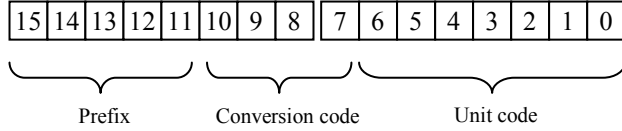
UNITS

The units deliver information about what a measured quantity is representing. So the kind of a measurement as well as its scaling is defined. The following structure covers all possible units. This definition is valid for the values of the appropriate MODBUS registers, which describe units. A visualization software can derive from this the correct measurement display.

Applications:

- Analog inputs: Measurand or meter unit
- Digital inputs: Meter unit

The unit structure covers all possibly selected inputs:



SI-Prefixes

Code	Name	Symbol	power
10 = 01010b	<i>Yotta</i>	Y	10 ²⁴
9 = 01001b	<i>Zetta</i>	Z	10 ²¹
8 = 01000b	Exa	E	10 ¹⁸
7 = 00111b	Peta	P	10 ¹⁵
6 = 00110b	Tera	T	10 ¹²
5 = 00101b	Giga	G	10 ⁹
4 = 00100b	Mega	M	10 ⁶
3 = 00011b	Kilo	k	10 ³
2 = 00010b	Hekto	h	10 ²
1 = 00001b	Deka	da	10 ¹
0 = 00000b	-	-	10 ⁰

Code	Name	Symbol	power
-1 = 11111b	Dezi	D	10 ⁻¹
-2 = 11110b	Zenti	C	10 ⁻²
-3 = 11101b	Milli	M	10 ⁻³
-4 = 11100b	Mikro	μ	10 ⁻⁶
-5 = 11011b	Nano	N	10 ⁻⁹
-6 = 11010b	Pico	P	10 ⁻¹²
-7 = 11001b	Femto	F	10 ⁻¹⁵
-8 = 11000b	Atto	A	10 ⁻¹⁸
-9 = 10111b	<i>Zepto</i>	Z	10 ⁻²¹
-10 = 10110b	<i>Yocto</i>	y	10 ⁻²⁴

Special case: Coding for decibel

For that the prefix code is used: 10000b = 20 * log(X/X0)

10001b = 10 * log(X/X0)

Modificat.	Date	Vis.:	Type: SINEAX CAM	Nr.: 31 / 34	author: 06.05.09 RR
			Description: Modbus/TCP interface	No: W 157471	

Unit code

Code	Description	Unit	
1	no unit		-
2	length	Meter	m
3	mass	Gram *)	G
4	time	Seconds	s
5	current	Ampere	A
6	temperature	Kelvin	K
7	Amount of substance	Mol	mol
8	luminous intensity	Candela	Cd
9	plane angle	(61850: Grad)	rad
10	plane angle	Radian	rad
11	solid angle	Steradian	sr
21	absorbed dose	Gray	Gy
22	activity	Becquerel	Bq
23	relative temperature		°C
24	dose equivalent	Sievert	Sv
25	electric capacitance	Farad	F
26	electric charge		As
27	electric conductance	Siemens	1/Ω
28	electric inductivity	Henry	H
29	electric potential	Volt	V
30	electric resistance	Ohm	Ω
31	energy	Joule	Ws
32	force	Newton	N
33	frequency	Hertz	Hz
34	illuminance	Lux	lx
35	luminous flux	Lumen	lm
36	magnetic flux	Weber	Wb
37	magnetic flux density	Tesla	T
38	power	Watt	W
39	pressure		N/ m ²
41	area		m ²
42	volume		m ³
43	velocity		m/s
44	acceleration		m/s ²
45	volume rate		m ³ /s
46	fuel efficiency		m/ m ³
47	moment of mass		M
48	density	*)	g/ m ³
49	viscosity		m ² /s
50	thermal conductivity		W/m K
51	heat capacity		J/K
52	concentration		ppm
53	rotational speed		s ⁻¹
54	angular velocity		rad s ⁻¹

Code	Description	Unit	
61	apparent power		VA
62	active power	Watt	W
63	reactive power		Var
64	phase angle		rad
65	power factor cos phi		-
66	volt seconds		Vs
67	volts squared		V ²
68	amp seconds		As
69	amps squared		A ²
70	amps squared time		A ² s
71	apparent energy		VAs
72	active energy		Ws
73	reactive energy		vars
74	magnetic flux	Weber	V/Hz
80	specific electrical resistance	Ohmmeter	Ωm
81	magnetic induction		A/m
82	current density		A/ m ²
83	molar mass		g/mol
84	molar volume		m ³ /mol
85	molar heat capacity		J/mol
86	electric charge	Coulomb	C
87	electric field strength		V/m
88	irradiation		J/ m ²
89	energy flux density		W/ m ²
90	radiant intensity		W/sr
91	radiance		W/sr*s ₂
92	luminance		cd/ m ²
93	quantity of light		lm*s
94	luminous exposure		lx*s
95	lens power	Dioptre	1/m
96	radiant flux		W
97	sound pressure		N/ m ²
98	sound intensity		W/ m ²
99	permeability		H/m
100	mechanical stress		N/ m ²
101	torque	Newton meter	Nm
102	spring rate		N/m
103	volume throughput		m ³ *s

*) The SI unit would be kg. But instead of kg g is used, because kilo is coded by the prefix.

Modificat.	Date	Vis.:	Type: SINEAX CAM	Nr.: 32 / 34	author: 06.05.09 RR
			Description: Modbus/TCP interface	No: W 157471	

Conversion code

The SI prefix is always related to the first unit (e.g. km/h)

The conversion code 0 represents the unit which is mentioned in the table of the unit codes.

Physical quantity	Code	Unit		Physical quantity	Code	Unit	
Temperature	0	Kelvin	K	Heat capacity	0	Kelvin	J/K
	1	Celsius	°C		1	Celsius	J/°C
	2	Fahrenheit	°F		2	Fahrenheit	J/°F
	3	Rankine	°R		3	Rankine	J/°R
Plane angle	0	Radiant	rad	Angular velocity	0		rad/s
	1	Grad	1°		1		°/s
	2	Minutes	1'		↕		
	3	Seconds	1''	Angular acceleration	0		rad / s ²
	4	Gon	gon		1		° / s ²
	5	Cent. degree	1 ^g				
	6	Cent. minute	1 ^c				
	7	Cent. second	1 ^{cc}				
Force	0	Newton	N	Torque	0	Newton meter	Nm
	1	Pond	p		1	Pondmeter	pm
	2	Dyn	dyn				
	3	pound-force	lbf				
Mass	0	Gram	g	Pressure	0		N/ m ²
	1	Ton	t		1	Pascal	Pa
	2	metr. carat	Kt		2	Bar	bar
	3	pound	lb		3		Torr
	4	ounce	oz		4	techn. atm.	at
	5	ton			5	phys. atm.	atm
	6	long ton			6	Meter water column	m WS
7	short ton		7	Millimeter mercury column	mm HG		
Luminous intensity	0	Candela	cd	Luminance	0		cd / m ²
					1	Stilb	sb
magnetic induction	0		A/m	magnetic flux	0	Weber	Wb
	1	Oersted	Oe		1	Maxwell	M
Induction	0	Tesla	T				
	1	Gauss	G				
without unit	0	-	-	Ionic dose	0	C / kg	
	1	Relation	-	1	Roentgen		
	2	Percent	%	Energy dose	0	Gray	Gy
	3	Parts per Million	ppm	1	Rad	rd	
	15	invalid	-	Activity	0	Becquerel	Bq
				1	Curie	Ci	

Modificat.	Date	Vis.:	Type: SINEAX CAM	Nr.: 33 / 34	author: 06.05.09 RR
			Description: Modbus/TCP interface	No: W 157471	

Physical quantity	Code	Unit			Physical quantity	Code	Unit	
mechanical stress	0 1 2		N/ m ² p/ mm ² p/ cm ²		Surface tension	0 1		N/m dyn/cm
Length	0 1 2 3 4 5 6 7	Meter inch foot yard mile Nautical mile Angström Light year	m in ft yd Mi Sm Å lj	⇔	Area	0 1 2 3 4 5 6 7	square inch square foot square yard square mile Ar Hectare Barn	m ² in ² ft ² yd ² mi ² a ha b
Volume	0 1 2 3 4 5 6 7 8 9	cubic inch cubic foot cubic yard cubic mile Litre gallon (UK) gallon (US) barrel bushels	m ³ in ³ ft ³ yd ³ mi ³ l gal gal	⇔	Volume meter	0 1 2 3 4 5 6 7	cubic inch cubic foot cubic yard cubic mile Litre gallon (UK) gallon (US)	m ³ in ³ ft ³ yd ³ mi ³ ls gal*s gal*s
Power	0 1 2 3 4 5 6	Watt Horse power	W J/s PS cal/s eV/s cal/h pm/s	⇔	Energy	0 1 2 3 4 5 6 7	Watt seconds Joule calorie Elektron volt Erg brit. term. unit Watt hour	Ws J PSh cal eV erg btu Wh
Reactive power	0		Var	⇔	Reactive energy	0 7		vars varh
Apparent power	0		VA	⇔	Apparent energy	0 7		VAs VAh
Luminous flux	0		lm	⇔	Quantity of light	0 7		lm*s lm*h
electric current	0		A	⇔	electric charge	0 7		As Ah
Time	0 1 2 3 4 5 ⇕	Seconds Minutes Hours Day Month Year	s min h d Mt Y	⇔	Velocity	0 1 2 3 4 5 6		m/s m/min m/h m/d m/Mt m/Y kn
Frequency	0 1 2 3 4 5		Hz 1/min 1/h 1/d 1/Mt 1/Y		Acceleration	0 1 2 3 4 5		m/s ² m/min ² m/h ² m/d ² m/Mt ² m/Y ²

Yellow marked are those units, which may be directly converted into the depending unit (e.g. P ⇔ E)

Modificat.	Date	Vis.:	Type: SINEAX CAM	Nr.: 34 / 34	author: 06.05.09 RR
			Description: Modbus/TCP interface	No: W 157471	